

Model Reductions with Special CSP Data

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Model reductions for stiff problems

- Consider the general initial-value problem:

$$\frac{d\mathbf{y}}{dt} = \mathbf{g}(\mathbf{y}; \varepsilon)$$

$$\mathbf{y}(t = 0) = \hat{\mathbf{y}}$$

Where \mathbf{y} and \mathbf{g} are N dimensional column vectors. The initial condition is arbitrary.

The problem is **stiff** when ε is asymptotically small.

For chemical kinetics ...

$$\mathbf{y} = \begin{bmatrix} H_2O \\ O \\ OH \\ \vdots \\ T \end{bmatrix} \quad \mathbf{g}(\mathbf{y}; \boldsymbol{\varepsilon}) = \sum_{r=1}^R \alpha_r \Omega^r(\mathbf{y}, k_r)$$

Where the α_r 's are the **stoichiometric** column vectors, and the $\Omega^r(\mathbf{y}; \boldsymbol{\varepsilon})$'s are the **kinetic rates** of the r-th reaction, respectively.

R is number of reactions. Usually, $R \gg N$.

The issues of interest...

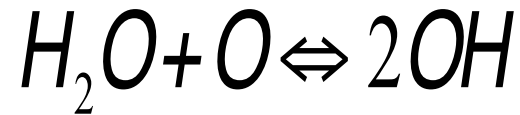
- Some of the reactions are very, very fast...
- We are interested in a much coarser time scale ... (the **stiffness** issue)
- We want to know who is doing what to whom at time t ... (the **insight** issue)
- Which kinetic rate parameters do we need to know accurately ... and which can we accept sloppiness ... (the **sensitivity** issue)
- Can we reduce the value of N ... (the **size** issue)

Paper/pencil vs computer

- When N is small (e.g. less than 10), one could use **paper/pencil** to do **singular perturbation asymptotics**. But **Quasi-steady approximation (QSA)** and/or **Partial Equilibrium approximation (PEA)** require insights and mathematical skills...
- When N is large, such problems are beyond the reach of classical paper/pencil analysis.
- **Computational singular perturbation (CSP)** is **programmable paper/pencil analysis**...

Chemical kinetics data

r-th
reaction:



$$\mathbf{y} = \begin{bmatrix} H_2O \\ O \\ OH \\ \vdots \\ T \end{bmatrix}$$

$$\alpha_r = \begin{bmatrix} -1 \\ -1 \\ +2 \\ 0 \\ \Delta h_r \end{bmatrix}$$

$$\Omega^r(\mathbf{y}) = k_r ([H_2O][O] - K_r [OH]^2)$$

A reaction is **fast** if k_r is very, very large...

Special CSP data $\alpha_r, \beta^r, \tau^r$.

$\Omega^r(\mathbf{y}; k_r), \alpha_r$ Given data of the r-th reaction.



These data are **reaction-specific!**

Row vector

$$\beta^r(\mathbf{y}) \equiv \tau^r \frac{\partial \Omega^r}{\partial \mathbf{y}} = \tau^r \left[\frac{\partial \Omega^r}{\partial [H_2O]}, \frac{\partial \Omega^r}{\partial [O]}, \frac{\partial \Omega^r}{\partial [OH]}, \dots, \frac{\partial \Omega^r}{\partial T} \right]$$

scalar

$$\tau^r(\mathbf{y}) \equiv \frac{1}{\frac{\partial \Omega^r}{\partial \mathbf{y}} \otimes \alpha_r} = \frac{1}{-\frac{\partial \Omega^r}{\partial [H_2O]} - \frac{\partial \Omega^r}{\partial [O]} + 2 \frac{\partial \Omega^r}{\partial [OH]} + \dots + \Delta h_f \frac{\partial \Omega^r}{\partial T}}$$

Note **physical dimension** of τ^r is **time**, and it is **defined** $\beta^r \otimes \alpha_r = 1$ so that

More special CSP data

$$\Gamma_{r'}^r(\mathbf{y}) = \beta^r \otimes \alpha_{r'}$$

$$r, r' = 1, \dots, R.$$

All elements of this matrix are **dimensionless O(1) numbers**.

The diagonal elements are unity by definition.

Fast-slow partitioning

- Once we have the $\tau^r(\mathbf{y})$'s on the fly, we can tentatively rank the R reactions on the fly.
- The reactions can be partitioned into fast and slow groups on the fly:

$$\mathbf{g}(\mathbf{y}; \varepsilon) = \sum_{m=1}^M \overset{\text{Fast reactions}}{\alpha_m \Omega^m(\mathbf{y}; k_m)} + \sum_{n=M+1}^R \overset{\text{Slow reactions}}{\alpha_n \Omega^n(\mathbf{y}; k_n)} \quad \varepsilon \equiv \frac{|\tau^M|}{|\tau^{M+1}|} \ll 1$$

Fast reactions Slow reactions
???

Question:

what happens to the fast reaction group after the fast reactions are exhausted?

$$\mathbf{g}(\mathbf{y}; \varepsilon) = \sum_{m=1}^M \alpha_m \Omega^m(\mathbf{y}; k_m) + \sum_{n=M+1}^R \alpha_n \Omega^n(\mathbf{y}; k_n)$$

- We are given **explicit algebraic formulas** for $\Omega^m(\mathbf{y}; k_m)$
- Differentiate it with respect to time:

$$\frac{d\Omega^m}{dt} = \frac{\partial \Omega^m}{\partial \mathbf{y}} \frac{d\mathbf{y}}{dt} = \frac{\beta^m}{\tau^m} * \mathbf{g} = \frac{1}{\tau^m} \left(\sum_{m'=1}^M \Gamma_{m'}^m \Omega^{m'} + \sum_{n=M+1}^R \Gamma_n^m \Omega^n \right)$$

- Define

$$\Theta_m^{m*} \equiv \left[\Gamma_{m^*}^m \right]^{-1} \quad \tau_m^{m*} \equiv \Theta_m^{m*} \tau^m \quad m, m^* = 1, \dots, M.$$

- **Exact differential equations** for the Ω^{m^*} 's are obtained:

$$\sum_{m=1}^M \tau_m^{m*} \frac{d\Omega^m}{dt} = \Omega^{m^*} - \Omega_{\infty}^{m^*}(\mathbf{y}; k_{slow}) \quad \Omega_{\infty}^{m^*}(\mathbf{y}; k_{slow}) \equiv - \sum_{n=M+1}^R \left(\sum_{m=1}^M \Theta_m^{m*} \Gamma_n^m \right) \Omega^n(\mathbf{y}; k_n)$$

These two equations are the foci of this paper!

CSP refinement procedures

- The leading order **converged CSP-refined** fast basis vectors can be obtained **analytically** in terms of the CSP data!

$$\mathbf{a}_m = \alpha_m, m=1, \dots, M.$$

They must be linearly independent.

$$\mathbf{b}^m = \sum_{m'=1}^M \Theta_{m'}^m \beta^{m'}, m=1, \dots, M.$$

These **converged** fast CSP-refined basis vectors are most useful for model reductions.

Exact reformulation of the problem

$$\frac{d\mathbf{y}}{dt} = \sum_{m=1}^M \alpha_m \Omega^m + \sum_{n=M+1}^R \alpha_n \Omega^n(\mathbf{y}; k_n)$$

$$\sum_{m'=1}^M \tau_{m'}^m(\mathbf{y}) \frac{d\Omega^{m'}}{dt} = \Omega^m - \Omega_{\infty}^m(\mathbf{y}; k_{slow})$$

Where $\tau_{m'}^m(\mathbf{y})$ and $\Omega_{\infty}^m(\mathbf{y}; k_{slow})$ are CSP data. negative and small

What happens when $\tau_{m'}^m(\mathbf{y})$ is asymptotically small?

how small is small?

The classical paper/pencil strategy

Neglect "higher order" terms:

$$\frac{dy}{dt} = \sum_{m=1}^M \alpha_m \Omega^m + \sum_{n=M+1}^R \alpha_n \Omega^n(\mathbf{y}; k_n)$$

$$\Omega^m = \Omega_{\infty}^m(\mathbf{y}; k_{slow}) + \sum_{m'=1}^M \tau_{m'}^m(\mathbf{y}) \frac{d\Omega^{m'}}{dt} \approx \Omega_{\infty}^m(\mathbf{y}; k_{slow})$$

negligible

The classical paper/pencil **reduced model** is:

$$\frac{dy}{dt} \approx \sum_{m=1}^M \alpha_m \Omega_{\infty}^m(\mathbf{y}; k_{slow}) + \sum_{n=M+1}^R \alpha_n \Omega^n(\mathbf{y}; k_n)$$

Note: the above equation does not depend on the fast k_m 's. **It is no longer stiff.**

A **new** strategy

Consider $\Omega^m, m=1, \dots, M,$ also as depending variables!

$$\frac{d\mathbf{y}}{dt} = \sum_{m=1}^M \alpha_m \Omega^m + \sum_{n=M+1}^R \alpha_n \Omega^n(\mathbf{y}; k_n)$$

$$\sum_{m'=1}^M \tau_{m'}^m(\mathbf{y}) \frac{d\Omega^{m'}}{dt} = \Omega^m - \Omega_{\infty}^m(\mathbf{y}; k_{slow})$$

- Use any credible **implicit** finite difference scheme to integrate the second equation.

This NEW reduced model is exact---
weaknesses of implicit schemes are tolerated.

Example: backward finite difference

Do not neglect anything:

$$\frac{d\mathbf{y}}{dt} = \sum_{m=1}^M \alpha_m \Omega^m + \sum_{n=M+1}^R \alpha_n \Omega^n(\mathbf{y}; k_n)$$

$$\Omega^m = \Omega_{\infty}^m(\mathbf{y}; k_{slow}) + \sum_{m'=1}^M \tau_{m'}^m(\mathbf{y}) \frac{d\Omega^{m'}}{dt}$$

use backward
finite
difference

where

$$\Omega_{\infty}^{m*}(\mathbf{y}; k_{slow}) \equiv - \sum_{n=M+1}^R \left(\sum_{m=1}^M \Theta_m^{m*} \Gamma_n^m \right) \Omega^n(\mathbf{y}; k_n)$$

$$\tau_{m'}^m \equiv \Theta_{m'}^m \tau^{m'}$$

Th solutions are exact.

Insight extractions...

- All “answers” are expressed in terms of

$$\alpha_r, \beta^r, \tau^r(\mathbf{y}), \tau_{m'}^m(\mathbf{y}), \Omega^n(\mathbf{y}; k_n), \Omega_\infty^m(\mathbf{y}; k_{slow}), \Theta_{m'}^m(\mathbf{y}), \Gamma_{r'}^r(\mathbf{y}), \dots$$

These are **physically/chemically meaningful** to knowledgeable investigators.

- **Laminar/turbulent diffusion terms can be handled...**
- **Effective stoichiometries** of the slow reactions are obtained...
- Reduced models are **not** unique.
- What happens at a different pressure?
What happens if some rate data were wrong?

The **slow invariant manifold**

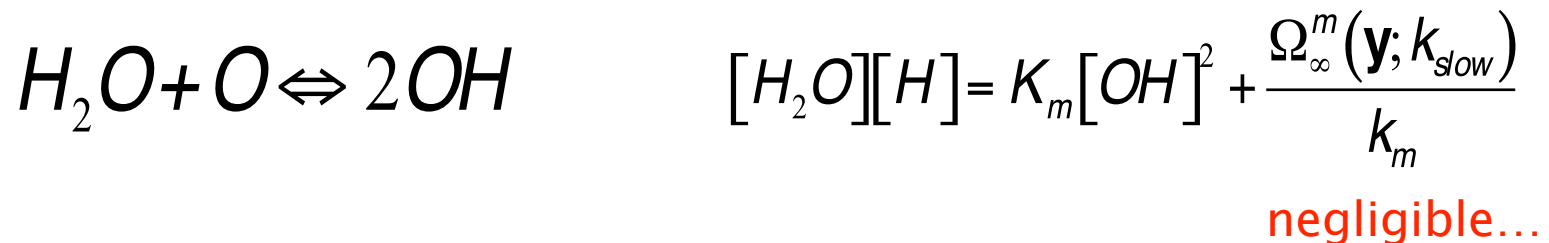
$$\Omega^m(\mathbf{y}; k_m) = \Omega_{forward}^m(\mathbf{y}; k_m) - \Omega_{reverse}^m(\mathbf{y}; k_m) \approx \Omega_{\infty}^m(\mathbf{y}; k_{slow})$$

Negligible

So

$$\Omega_{forward}^m(\mathbf{y}; k_m) \cong \Omega_{reverse}^m(\mathbf{y}; k_m) + \Omega_{\infty}^m(\mathbf{y}; k_{slow})$$

provides M algebraic equations which can replace M differential equations (of the CSP radicals). Note: the above is independent of k_m .



What can we learn from the CSP numbers?

- The issues: **stiffness, insights, sensitivities, size.**
- All important results are **analytically** expressed in terms of the CPS data. The most informative CSP data is $\Theta_m^{m*} \equiv [\Gamma_{m*}^m]^{-1}$.
- Provide guidance on how to **intelligently** exploit $\Omega^m(\mathbf{y}; k_m) = \Omega^m(t), m=1, \dots, M$.
These provide M **algebraic equations** for the N components of \mathbf{y} on the fly.
- Conservation of atomic elements and very slow reactions (i.e. large $\tau^n(\mathbf{y}; k_n)$'s) are not exploited...but may be exploited if so desired.

Computational Singular Perturbation

- Do not need to neglect things...
- Identify unimportant terms...in the derived analytical formulas...
- Take advantage of numerical algorithms being involved...
- Use dimensionless numbers...
- Remember...the important issue is: what can we learn from the computed numbers?

Special CSP Data

$$\alpha_r, \beta^r(\mathbf{y}), \tau^r(\mathbf{y}), \Theta_{m'}^m(\mathbf{y}), \tau_{m'}^m(\mathbf{y}), \dots$$

Leading order converged CSP-refined fast basis vectors are analytically found for chemical kinetics problems ...

$$\sum_{m'=1}^M \tau_{m'}^m(\mathbf{y}; k_{m'}) \frac{d\Omega^{m'}}{dt} = \Omega^m - \Omega_{\infty}^m(\mathbf{y}; k_{slow}), \quad m = 1, \dots, M.$$

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